

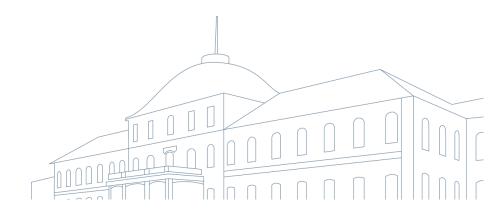
# Der Blick über den Zaun: KI als Gamechanger in der Landwirtschaft?

44. Freiburger Winterkolloquium Forst und Holz | Albert-Ludwigs-Universität Freiburg | 30.01.2025

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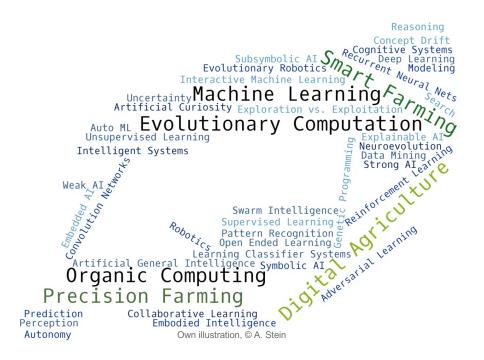




## **Outline**

### ■ Al in agriculture?

- Today: Agricultural AI applications
- Tomorrow: Research activities
- Aspects of getting there



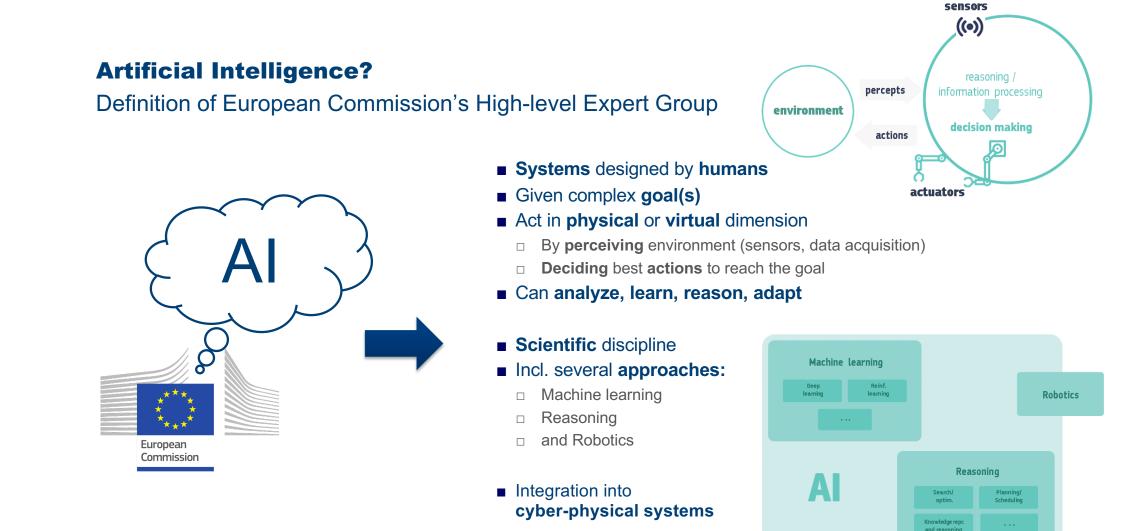


Figure sources: The European Commission's HIGH-LEVEL EXPERT GROUP ON ARTIFICIAL INTELLIGENCE, 2019, Available online: https://digital-strategy.ec.europa.eu/en/library/ethicsguidelines-trustworthy-ai (last 25.01.2025)

# **Artificial Intelligence?**

AI Act defines AI as follows



# EU Artificial Intelligence Act



"(1) 'AI system' means a machine-based system that is designed to operate with varying levels of autonomy and that may exhibit adaptiveness after deployment, and that, for explicit or implicit objectives, infers, from the input it receives, how to generate outputs such as predictions, content, recommendations, or decisions that can influence physical or virtual environments; Related: <u>Recital 12</u>"

Source: https://artificialintelligenceact.eu/article/3/ (last accessed 25.01.2025)



# **Artificial Intelligence?**

AI Act defines AI as follows – Recital 12



# EU Artificial Intelligence Act

Source: https://artificialintelligenceact.eu/recital/12/ (last accessed 15.10.2024)

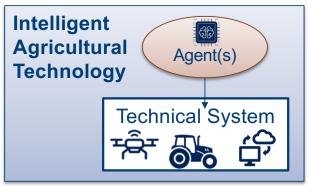
The notion of 'AI system' in this Regulation should be clearly defined and should be closely aligned with the work of international organisations working on AI to ensure legal certainty, facilitate international convergence and wide acceptance, while providing the flexibility to accommodate the rapid technological developments in this field. Moreover, the definition should be based on key characteristics of AI systems that **distinguish it from simpler** traditional software systems or programming approaches and should not cover systems that are based on the rules defined solely by natural persons to automatically execute operations. A key characteristic of AI systems is their capability to infer. This capability to infer refers to the process of **obtaining the outputs**, such as **predictions**, content, recommendations, or decisions, which can influence physical and virtual environments, and to a capability of AI systems to derive models or algorithms, or both, from inputs or data. The techniques that enable inference while building an AI system include machine learning approaches that learn from data how to achieve certain objectives, and logic- and knowledge-based approaches that infer from encoded knowledge or symbolic **representation** of the task to be solved. The capacity of an AI system to infer transcends basic data processing by enabling learning, reasoning or modelling. The term 'machine**based**' refers to the fact that **AI systems run on machines**. The reference to explicit or implicit objectives underscores that AI systems can operate according to explicit defined objectives or to implicit objectives. The objectives of the AI system may be different from the intended purpose of the AI system in a specific context. For the purposes of this Regulation, **environments** should be understood to be the **contexts in which the AI** systems operate, whereas outputs generated by the AI system reflect different functions performed by AI systems and include predictions, content, recommendations or **decisions**. AI systems are designed to operate with **varying levels of autonomy**, meaning that they have some degree of independence of actions from human involvement and of capabilities to operate without human intervention. The **adaptiveness** that an AI system could exhibit after deployment, refers to **self-learning capabilities**, allowing the **system to** <mark>change while in use</mark>. AI systems can be used on a **stand-alone basis** or as a **component of a** product, irrespective of whether the system is physically integrated into the product (embedded) or serves the functionality of the product without being integrated therein (non-embedded).



#### **Our perspective on AI in agriculture**

Pursuit of building Intelligent Agricultural Technology

"Al in Agriculture is the scientific discipline of designing intelligent agents (*Al programs*) for utilization in technical systems of a digitized agriculture with the aim to relieve farmers of tedious, timeconsuming, risky or overly complex tasks and at the same time optimizing agricultural processes in terms of their resource efficiency, working quality, resilience and in turn sustainability."



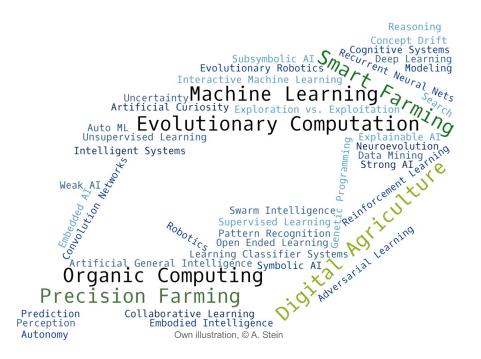
Own illustration, © A. Stein

- "Technical system": An engineered system built for serving a certain purpose, i.e., to achieve a certain task. Examples from agriculture:
  - Tractors and adaptable implements
  - □ UAVs for remote sensing / crop monitoring
  - □ Field robots for plant production purposes
  - Milking robots or barn cleaning robots
  - Climate and ventilation control systems
  - □ Surveillance systems in pigsty or cattle barns
  - □ Agricultural Information Systems (FMIS, GIS, etc.)
  - □ ...
- "Intelligent system": A technical system endowed with AI agents (i.e., programs) to possess properties such as
  - □ *adaptivity* to varying conditions (e.g., weather, soil)
  - □ *robustness* against unexpected events / disturbances
  - flexibility to changed goals and constraints (e.g. due to seasonal or policy changes)



## **Outline**

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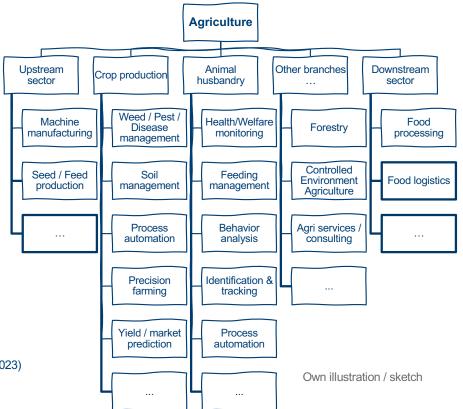


## **Applications of AI in agriculture**

Al's potential omnipresent in agriculture

#### Enabling trends and drivers:

- □ Ongoing **disruptive Al advancements** since 2010s
- □ Data availability due to smart/digital agriculture
- Continually improving sensor technology
- Embedded computing units have become more computationally powerful and `Al-ready'
- Combined with more efficient and `off-the-shelf' available Al models
- □ **Research programs** have been funded recently by institutions such as BMEL, BMWK, BMBF, DFG ...
- Most applications in crop production today (cf. Ryan et al. 2023)
- Much AI research in livestock and other sectors





## **Promises of AI in agriculture**

# Current technology still highly depends on manual operations and decisions

- □ **Limited human capacity** for manual analysis
- e.g., determining the nutritional state and demand of every individual plant

#### human labor through higher automation

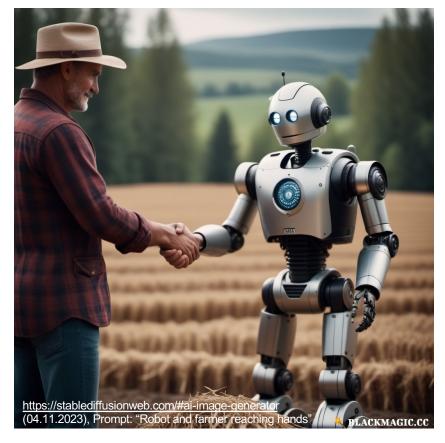
- □ Addresses labor shortage
- Role shift: Concentrate on important tasks

#### Analysis and decision capabilities

- Better decision support and advice
- Higher spatio-temporal resolution

#### > ↑ efficiency + sustainability + resilience

- □ Ensure **food security** (higher productivity)
- Still reducing negative environmental impacts





# **`AgBots' – Robots for agricultural field work**

Examples of two commercially available types

 Smaller, self-propelled machines specialized to (few) specific task(s)



Source: FarmingGT Video, Farming Revolution Website, URL: https://farming-revolution.com/static/54e6aa1256cc235d368b1777eb4f24f1/hero\_15s.mp4 (25.01.2025)

 Driverless tractor with conventional implements



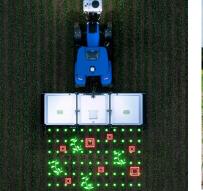
Source: AgXeed Video, Agxeed Website, URL: https://www.agxeed.com/wpcontent/uploads/2024/05/Ploughing-testingusecase.mp4 (25.01.2025)



# **Al-assisted crop production**

Weed control solutions

- Al-based weed detection
- Plant-individual precision and application
- Herbicide savings up to ~90% possible
- Variants:
  - □ **One-stage:** New smart implements
  - □ **Two-stage**: Air-borne mapping + application

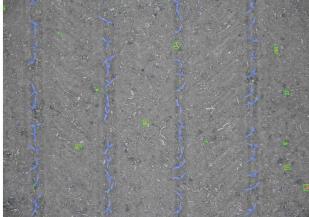


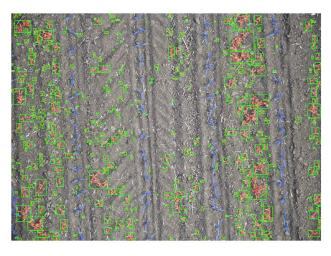
Source: Ecorobotix Website, URL: https://ecorobotix.com/de/plant-by-plant-kisoftware/ (last 25.01.2025)





Source: SAM DIMENSION, permission to reuse material granted





Unkrauterkennung (rot) mittels "künstlicher Intelligenz" Luftbildern in Mais (blau) zu EC 13. Grüne Rechtecke zeigen erkannte Unkrautpositionen. Links wenig Verunkrautung, rechts starke Verunkrautung.

# **Al-assisted crop production**

Tools to support harvesting

- Robotic fruit harvest with tethered drones
- Automated loading during forage harvest
- In-process grain quality assessment
- Using computer-vision and machine learning:
  - Classifying and localizing ripe fruits
  - □ Detecting trailer and fill status → Discharge arm control
  - □ Segmenting broken grain and foreign material



Source: Tevel-Tech Press Release, URL: <u>https://www.tevel-tech.com/press-release-tevel-partners-with</u> <u>unifrutti-expands-to-south-america/</u> (25.01.2025)



Source: John Deere Website, URL: <u>https://www.deere.com/assets/images/region-2/campaigns/ag-turf/grain-quality-guaranteed/r4f000511-c1-lsc.jpg</u> (25.01.2025)

# **Al-assisted livestock farming**

# Herd management and tools

- Animal health monitoring and tracking
  - □ E.g., Lameness, calving
- Automated recognition of parameters
  - Herd activity and animal distribution
  - Average weight estimation
- Barn climate reports and control
- Robotic applications:
  - □ Forage robots
  - □ Floor / barn cleaners
  - □ Milking robots
- Recommendation to farmers
- Higher husbandry process automation
- Better and more timely insights on barn dynamics



Source: Big Dutchman WeightCheck, Website, URL: https://www.bigdutchmanusa.com/en/pig-production/products/growingand-finishing/sorting/weightcheck/ (26.01.2025)



Source: Vetvise Website, URL: https://i0.wp.com/vetvise.com/wpcontent/uploads/2024/04/Website\_Gefluegel-3.png?resize=768%2C768&ssl=1 (last 26.01.2025)



Source: Lely Zeta KI-Stallmonitor, Lely Website, URL: https://www.lely.com/media/filer\_public\_thumbnails/filer\_public/a9/f9/a9f906ed-f27c-4157-b4fc\_fa\_tb\_fheth\_tele\_i-hern-f486/2-8-rg-ipt\_\_P9/2520\_q70\_cropsmart\_subsampling-2\_upscale.jpg (26.01.2025)

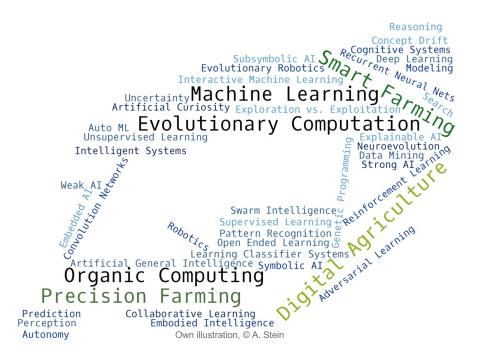


Source: **HIT Active Cleaner** Pferdeäpfel-Roboter, URL: https://aktivstall.de/wpcontent/uploads/2023/01/aktivstallroboter\_800\_1.jpg (26.01.2025)



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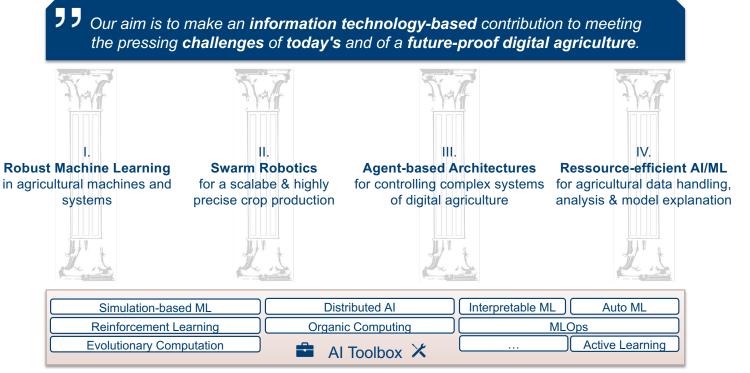
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# **Artificial Intelligence in Agricultural Engineering**

Our department's research statement



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<sup>44.</sup> Winterkolloquium Forst und Holz



# I. Robust machine learning & III. Agent-based Architectures

# Intelligent Secondary Tillage Control

#### Observation

 □ Agricultural machines often not fully utilized → Performance Gap

#### Challenges

- □ Controlling these machines optimally is complex
- Variability in soil conditions would require continual monitoring and adaptation of machine parameters

## > Approach

- □ Intelligent Control Architecture  $\rightarrow$  Organic Computing
- □ Model the environment-machine response
  → Deep Learning
- □ Train an intelligent agent to control the machine → Reinforcement Learning



- Digitization of the sowing process
- Development of an ICT architecture with a focus on fault tolerance for resilient farm operations
- Performance gap reduction of the involved machines/implements (on farm and inter-farm)
- □ Reduce **operation complexity** for the driver



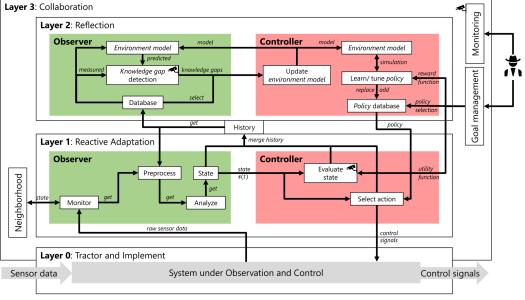


## I. Robust machine learning & III. Agent-based Architectures

Intelligent Secondary Tillage Control

- Design of an intelligent agent architecture
- Based on the principles of Organic Computing
- Observer/Controller-Architecture





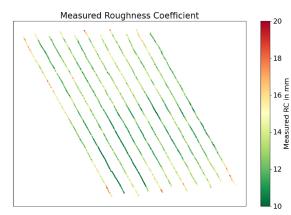
Stein, A., & Boysen, J. (2025). Organic Computing for Intelligent Agricultural Technology: Perspective and Case Study. Agricultural engineering.Eu, 80(1). https://doi.org/10.15150/ae.2025.3331

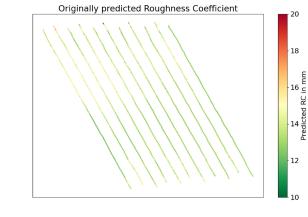


# I. Robust machine learning & III. Agent-based Architectures

## Intelligent Secondary Tillage Control

- Soil-machine response model
  - □ Collect in situ dataset in the real world
- Predicts next environment state based on state and machine configuration
  - □ Soil roughness, Engine fuel rate, Engine torque utilization
- Basis for creating control agent using model-based Reinforcement Learning





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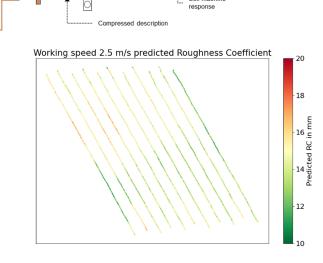
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Pre

RGBD image

Machine configuration

& context information



TITIT

Soil-machine

Jonas Boysen, Lucas Zender, Anthony Stein, Modeling the soil-machine response of secondary tillage: A deep learning approach, Smart Agricultural Technology, Volume 6, 2023, 100363, https://doi.org/10.1016/j.atech.2023.100363



# **II. Swarm robotics on agricultural fields**

## Why agricultural swarm robotics?

- ➤ Scaling potential → *flexibility*
- ≻ Less depedence on single machines but compensation of failed machines
   → robustness
- ➤ Smaller machines → soil protection
- High potential seen in small-scale cultivation or spot farming systems
- Smaller machines usually work at lower speeds but can reach higher working quality (cf. e.g., Griepentrog & Stein (2024))
- Area capacity (dt. Flächenleistung) can be achieved by increasing number of robots

 Example of a small agricultural robot `Phoenix' developed in Hohenheim



Source: Phoenix robot, H.W. Griepentrog, Uni Hohenheim, FG Verfahrenstechnik in der Pflanzenproduktion.

Griepentrog HW, Stein A (2024) Comparison of Robot Concepts for New Sustainable Crop Production Systems. Smart Agricultural Technology :100499. https://doi.org/10.1016/j.atech.2024.100499

# **II. Swarm robotics on agricultural fields**

# First approach: Simulation-based study

#### ■ Simulate scalable robot swarms at process level

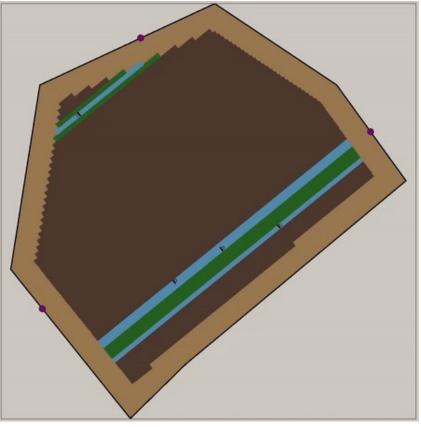
- Energy charge level & consumption
- Seed level & seed rate
- Logistic points to refill & charge
- Working width
- Turning radius  $\square$
- $\rightarrow$  according to the model of the **Phoenix robot**

#### **Comparison**: Swarm vs. conventional machine

- Metrics for determining the potential
- Area capacity
- $\frac{\text{machined area}}{\text{overall work time}} \begin{bmatrix} ha\\ h \end{bmatrix}$ Field efficiency *effective work time* [%]

#### Evaluate:

- Performance of **fully decentralized swarm coordination** (self-organization) with centralized and hybrid approaches
- Impact of individual robot failures on performance metrics



Source: Swarm robot simulation. Dept. Artificial Intelligence in Agricultural Engineering, Uni Hohenheim



# **IV. Resource-efficient AI for agricultural applications**

# GenAI-based training data creation

#### Observation:

 Al models need vast amounts of representative training data to become robust

#### Challenges:

- Manual annotation / labelling effort too high
- □ Lack of diversity in training sets → heterogeneous local conditions
- □ Imbalances in the class distributions →
  e.g., visible weeds vs. crops

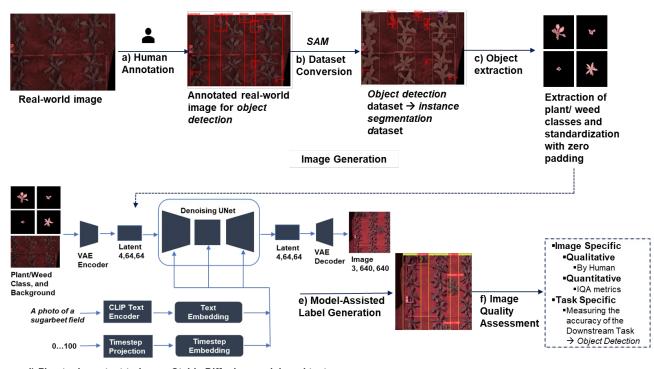
#### > Approach: Increase data efficiency

- Annotate fewer training images
- Use GenAl models to generate synthetic training data
- □ **Mix** with **real data** to improve downstream task
- **GEFÖRDERT VOM** Bundesministerium Project `HoPla' für Bildung und Forschung DEUTSCHLAND Increase weed detection accuracy and speed Focus on economically highly relevant crops Our contributions: Reduce manual data annotation effort (data efficiency) Compress large AI models and distill knowledge into computationally efficient models (inference efficiency) BOSCH 0000 Actively associated: **Diaital Farmina** Solutions AMAZONE powered by BASF



# **IV. Resource-efficient AI for agricultural applications**

GenAI-based training data creation



**Dataset Transformation** 

d) Fine-tuning a text-to-image Stable Diffusion model, and textguided image generation

Modak, S., Stein, A. (2024). Synthesizing Training Data for Intelligent Weed Control Systems Using Generative AI. In: Architecture of Computing Systems. ARCS 2024. Lecture Notes in Computer Science, vol 14842. Springer, Cham. https://doi.org/10.1007/978-3-031-66146-4\_8

Modak, S., Stein, A. (2024) Enhancing weed detection performance by means of GenAI-based image aug Mentatork All Proceedings of Computer Visits and Plant Phenotyping (CVPPA) Workshop, ECCV Workshops, to appear, Springer, Preprint: http://arxiv.org/abs/2411.18513



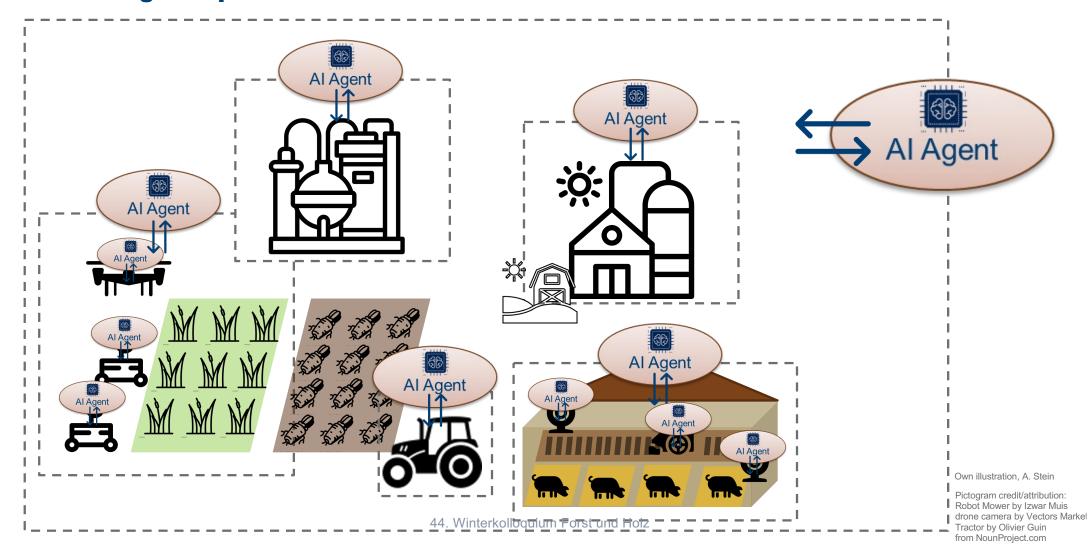
# **IV. Resource-efficient AI for agricultural applications**

GenAI-based training data creation



UNIVERSITY OF HOHENHEIM

# **Thought experiment**



Agri-food system as complex interwoven social-ecological system which requires:

Al Agent

Oisturbances

- ➢ Systemic process understanding and optimization → distributed AI
- ➢ Inter- & transdisciplinary approaches → transformative perspective
- ➢ Interplay between human and artificial intelligence → Hybrid AI

See also:

Covernance

Agent

AI Agent

Berger, T., Gimpel, H., Stein, A. *et al.* **Hybrid intelligence for reconciling biodiversity and productivity in agriculture.** *Nature Food* **5**, 270–272 (2024)

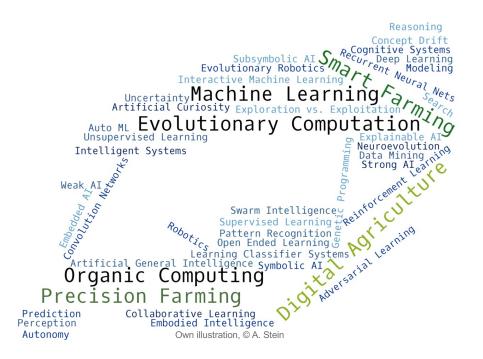
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Own illustration, A. Stein Landschaftsaufnahme: frei verfügbar über pexels.com



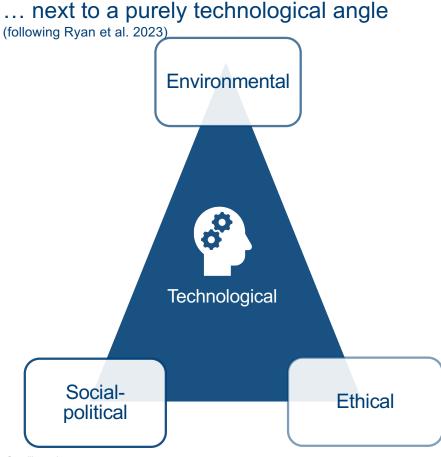
## **Outline**

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# Systemic view on agriculture



Own illustration

- Agriculture as a social-ecological system
- Technological innovations need financially feasible solutions to be adopted
- Next to technological aspects, further dimensions matter
  - Socio-political conditions, e.g., subsidies, acceptance
  - Environmental boundaries, e.g., Biodiversity, soil degradation
  - □ Ethical concerns, e.g., risk for digital divide
- Transdisciplinary approach deemed key for successful technology adoption and potential realization

# **Digital agriculture in education**

#### Educate in digital competences

- Bring next gen. famers closer to possibilities of digital technologies
- Increase trust in digital technologies, e.g., AI

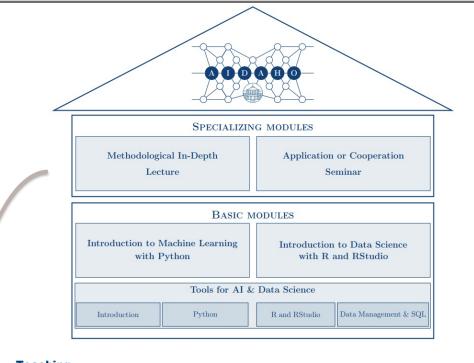
#### Strengthen data literacy

- Data management, security, privacy
- But: No need to become 'data scientists'
- Lower reservation, increase data sovereignty  $\geq$

#### Create readiness to self-assess suitability of new digital tools

- □ ... with their **potentials**, **challenges** and **risks**
- Better basis for farm-individual adoption  $\geq$ decisions

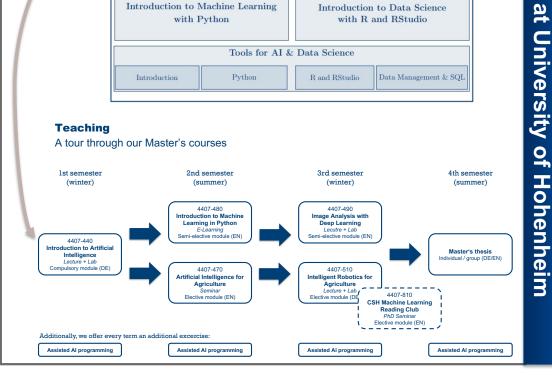




Some activities

#### Teaching

A tour through our Master's courses





#### **Summary**

# Is AI a gamechanger in agriculture as of today?

#### Agricultural Al applications in place

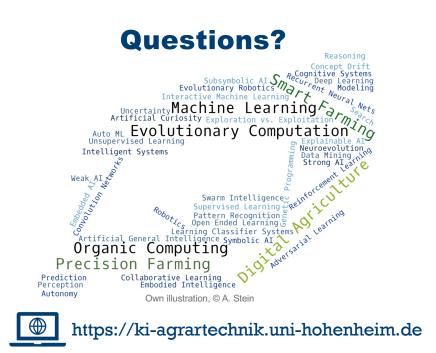
- Research spans all agricultural sectors
- First commercial solutions using isolated Al technology to increase automatization
- But: Much R&D ahead to leverage Al's full potential

#### Systems thinking: Beyond isolated AI techniques

- Untapped potential
- Integrating well-designed AI agents into Intelligent AgTech systems
- Connecting these AI-based systems across the technological scales of digital agriculture

#### • Further aspects of changing the game

- □ Education: Early training of digital competences
- Transdisciplinary research: Actively involve actors





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- Berger, T., Gimpel, H., Stein, A. *et al.* Hybrid intelligence for reconciling biodiversity and productivity in agriculture. *Nature Food* 5, 270–272 (2024)



#### List of external figure and video sources

Slide 3: The European Commission's HIGH-LEVEL EXPERT GROUP ON ARTIFICIAL INTELLIGENCE, 2019, Available online: https://digital-strategy.ec.europa.eu/en/library/ethics-guidelines-trustworthyai (last 25.01.2025)

Slides 4-5: EU Artificial Intelligence Act Logo, URL: https://artificialintelligenceact.eu/article/3/ (last 25.01.2025)

Slide 9: https://stablediffusionweb.com/#ai-image-generator (04.11.2023), Prompt: "Robot and farmer reaching hands"

Slide 10:

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Slide 12:

Tevel Roboter Image: Tevel-Tech Press Release, URL: https://www.tevel-tech.com/press-release-tevel-partners-with-unifrutti-expands-to-south-america/ (last 25.01.2025)

John Deere Grain Quality Control Image: John Deere Website, URL: https://www.deere.com/assets/images/region-2/campaigns/ag-turf/grain-quality-guaranteed/r4f000511-c1-lsc.jpg (last 25.01.2025) Slide 13:

Image Lely Zeta KI-Stallmonitor, Lely Website, URL: https://www.lely.com/media/filer\_public\_thumbnails/filer\_public/a9/f9/a9f906ed-f27c-4157-b4fc-fc7b1fbe35dc/lely-zeta-i-barn-608120-2-rg.jpg\_900x520\_q70\_crop-smart\_subsampling-2\_upscale.jpg (last 26.01.2025)

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Big Dutchman WeightCheck Image, Big Dutchman Website, URL: https://www.bigdutchmanusa.com/en/pig-production/products/growing-and-finishing/sorting/weightCheck/ (last 26.01.2025)

Image of HIT Active Cleaner Pferdeäpfel-Roboter, URL: https://aktivstall.de/wp-content/uploads/2023/01/aktivstallroboter\_800\_1.jpg (last 26.01.2025)

Slide 19: Phoenix robot, H.W. Griepentrog, Uni Hohenheim, FG Verfahrenstechnik in der Pflanzenproduktion.

Slide 24: Pictograms from from NounProject.com, Robot Mower by Izwar Muis, drone camera by Vectors Market, Tractor by Olivier Guin

Slide 25: Landscape image: freely available on pexels.com



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